



Robotics: Course organization

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Outline of the course

- ▶ Manipulation robotics
 - ▶ Literature: Kevin M. Lynch and Frank C. Park: **Modern Robotics: Mechanics, Planning, and Control**



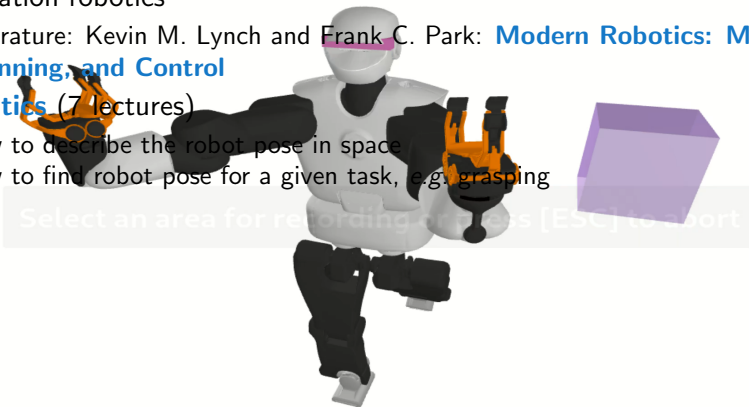
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- ▶ **Kinematics** (7 lectures)
 - ▶ how to describe the robot pose in space
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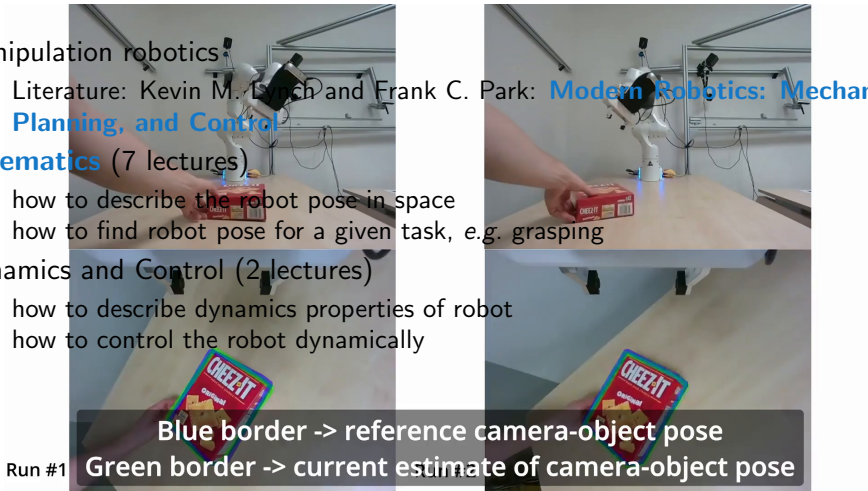
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 - ▶ how to describe dynamics properties of robot
 - ▶ how to control the robot dynamically



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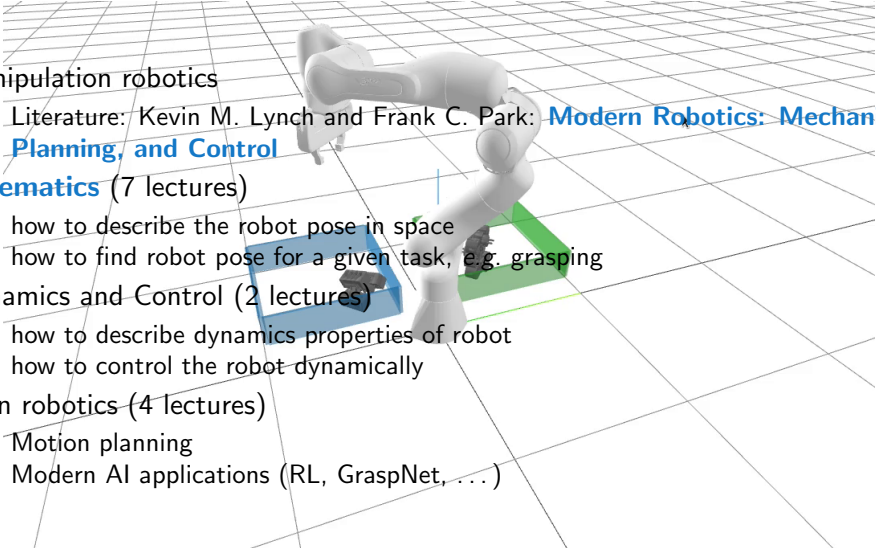


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 - ▶ Modern AI applications (RL, GraspNet, ...)



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Laboratories

- ▶ Program robotics toolbox in Python
 - ▶ combination of work in lab and homework
 - ▶ automatic evaluation with unit-tests
 - ▶ labs are in KN:E-132
 - ▶ labs follow-up the lectures, **study the lecture before lab**



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- ▶ Solving practical project assignment on real industrial robot
 - ▶ robots are located in CIIRC:JP:B-415
 - ▶ brute reservation system
 - ▶ optional (recommended) consultations
 - ▶ safety in the 6th week is mandatory to attend



Evaluation

- ▶ Homework:
 - ▶ four mandatory assignments: 10 points
 - ▶ four optional assignments: max 10 points
- ▶ Final project: max 20 points
- ▶ Tests during semester (8. and 14. week): max 20 points
- ▶ Exam: max 40 points



Teachers

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 - ▶ Final project on real robots
 - ▶ Vladimír Smutný
 - ▶ Pavel Krsek

