

Robotics: Final Project

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Overview

- Motivation: practical experience with real hardware
- Team of two students
- Two options for the project
 - Cubes reorganization: pick-and-place with 6 DoF robot and vision
 - Drawing with a robot: draw with 4 DoF robot



Option #1: Cubes reorganization

External camera, 2 robots (CRS97, CRS93)





Option #1: Cubes reorganization

- Desks with AruCo markers on the top (CSV provided)
- ► Goal: transfer all cubes between holders





Variant A: planar problem, one desk (7 points)





- Variant A: planar problem, one desk (7 points)
- Variant B: planar problem, cubes reorganization (10 points)





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- Variant B: planar problem, cubes reorganization (10 points)
- Variant C: non-planar problem (15 points)





- Variant A: planar problem, one desk (7 points)
- Variant B: planar problem, cubes reorganization (10 points)
- Variant C: non-planar problem (15 points)
- Variant D: rotation by 7 or 15 degrees (20 points)





Option #2: Draw with a robot

- Draw curves from the image template
- No camera needed
- Robot Bosch (SCARA)









Input

- Input is an image that contains a curve
- Dimmension of a iamge is 1000×1000 px
- ▶ 1 px corresponds to 1 mm





 Variant A-1: one curve in intersection of the red and green (4 points)





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- Variant A-N: more curves (6 points)





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- Variant B-1/N: one curve in either red or green (6/7 points)





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- Variant D-1/N: one curve in robot workspace (blue) (14/15 points)







Sharing the resources: reservation system in BRUTE





Laboratories

- Sharing the resources: reservation system in BRUTE
- Consultations
 - During the labs: one of TAs (Krsek, Smutny) is prepared on a phone
 - Other timeslot: contact all TAs by email





Delivering final project

- Technical report and demonstration
- Report needs to be uploaded in advance
- Reservation system for the last week of the semester and exam-period
- Contact us if you want to deliver sooner

