

Robotics: Final Project

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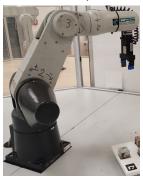
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Overview

- ▶ Motivation: practical experience with real hardware
- Team of two students
- ► Two options for the project
 - Cubes reorganization: pick-and-place with 6 DoF robot and vision
 - Drawing with a robot: draw with 4 DoF robot

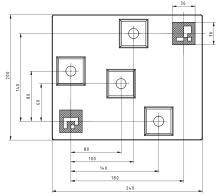
Option #1: Cubes reorganization

External camera, 2 robots (CRS97, CRS93)



Option #1: Cubes reorganization

- Desks with AruCo markers on the top (CSV provided)
- ► Goal: transfer all cubes between holders





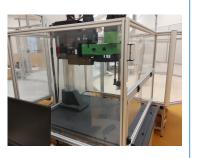
Option #1: Cubes reorganization, variants

- Variant A: planar problem, one desk (7 points)
- Variant B: planar problem, cubes reorganization (10 points)
- ► Variant C: non-planar problem (15 points)
- ► Variant D: rotation by 7 or 15 degrees (20 points)

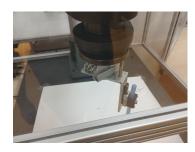


Option #2: Draw with a robot

- ▶ Draw curves from the image template
- ► No camera needed
- ► Robot Bosch (SCARA)

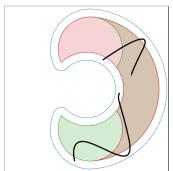






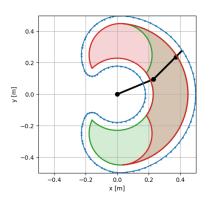
Input

- ▶ Input is an image that contains a curve
- ▶ Dimmension of a lamge is 1000×1000 px
- ▶ 1 px corresponds to 1 mm



Option #2: Draw with a robot, variants

- ➤ Variant A-1: one curve in intersection of the red and green (4 points)
- ► Variant A-N: more curves (6 points)
- Variant B-1/N: one curve in either red or green (6/7 points)
- Variant C-1/N: one curve in union of red and green (8/10 points + 1 point for continuity)
- ➤ Variant D-1/N: one curve in robot workspace (blue) (14/15 points)



Laboratories

- ▶ Sharing the resources: reservation system in BRUTE
- Consultations
 - During the labs: one of TAs (Krsek, Smutny) is prepared on a phone
 - ▶ Other timeslot: contact all TAs by email



Delivering final project

- ► Technical report and demonstration
- Report needs to be uploaded in advance
- ▶ Reservation system for the last week of the semester and exam-period
- ► Contact us if you want to deliver sooner